

NOM :

Prénom :

Classe :

Exercice
La projection orthogonale

CI 1 : Les techniques et outils de représentation du réel



Consignes :

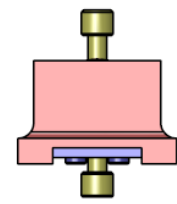
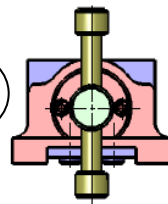
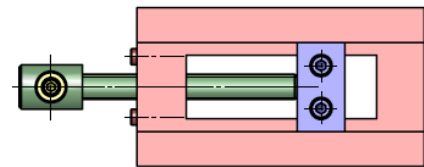
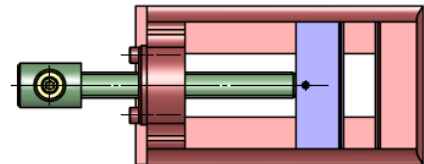
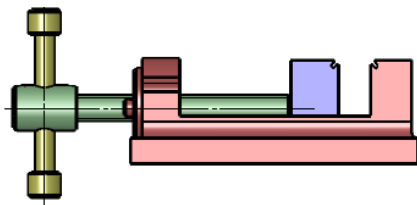
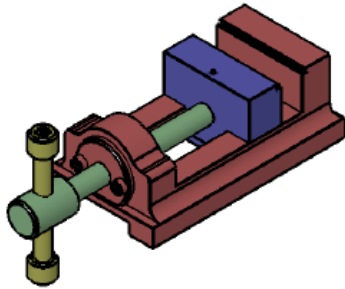
Pour chaque système ci dessous,
Repérer par la lettre correspondante
les quatre vues manquantes du dessin
d'ensemble.

Compétence :

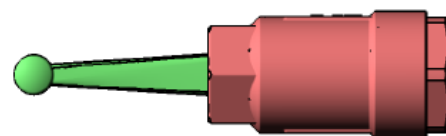
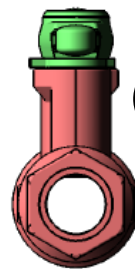
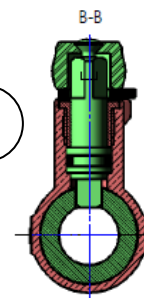
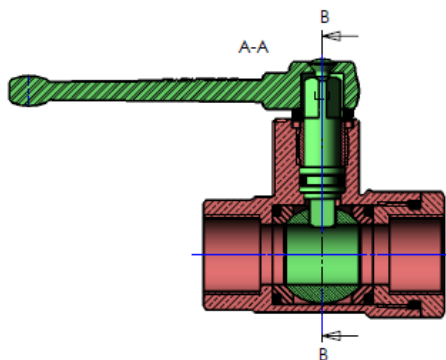
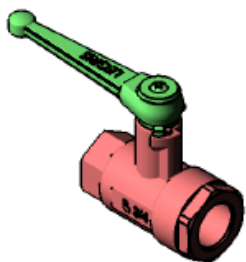
Associer une même
surface ou un même
volume dans plusieurs
vues d'une mise en plan.

Autonomie

Système étau



Système vanne



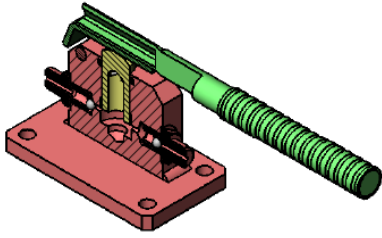
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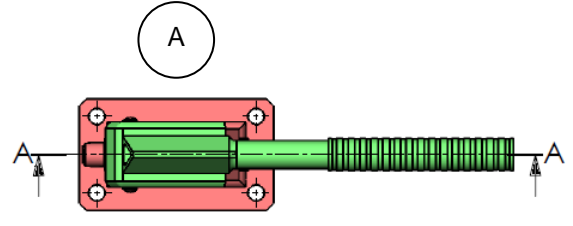
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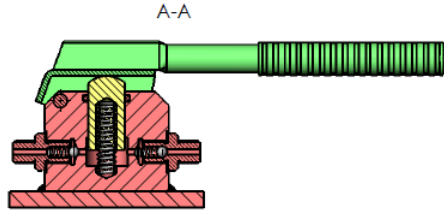
Système pompe hydraulique



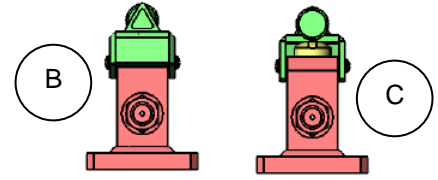
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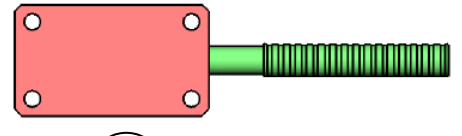
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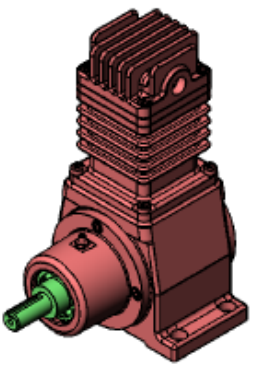


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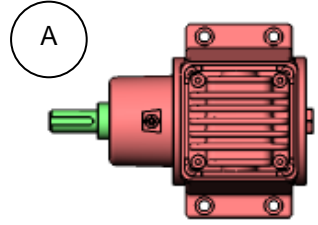


D

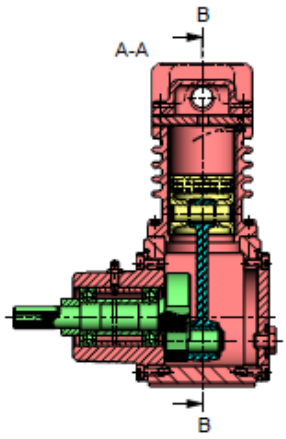
Système compresseur



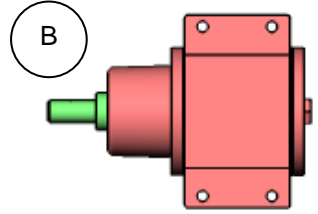
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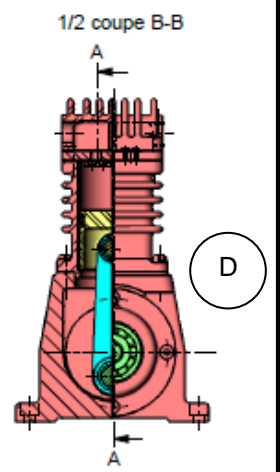
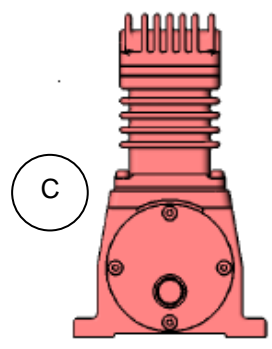
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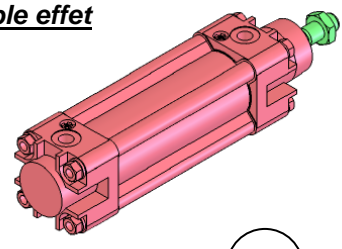
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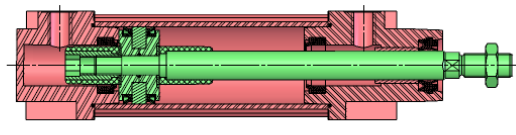
Systeme vérin double effet



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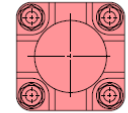
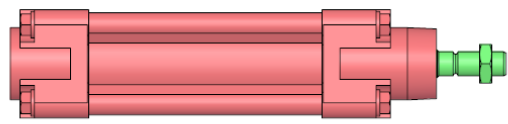
COUPE A-A



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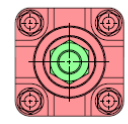
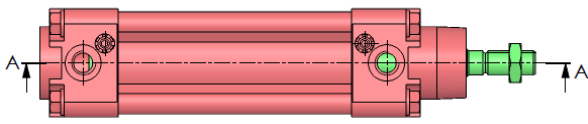
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A



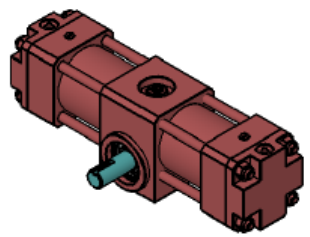
B

C



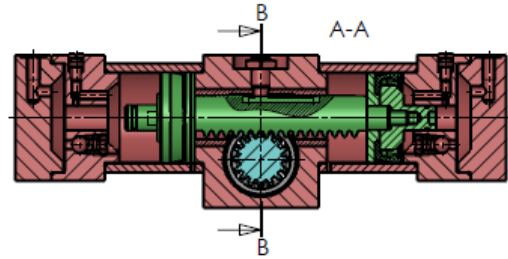
D

Systeme vérin rotatif



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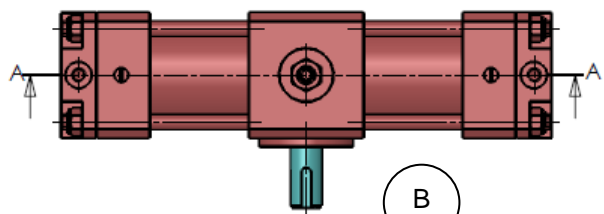
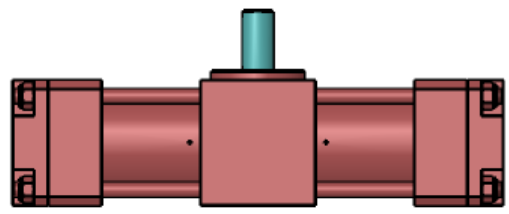
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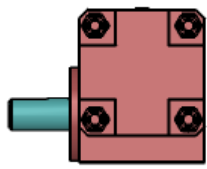
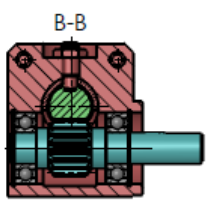
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A



B

C



D

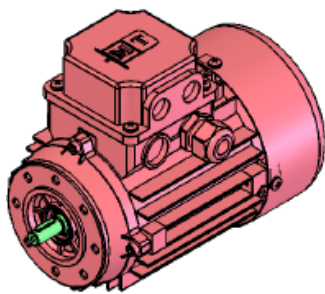
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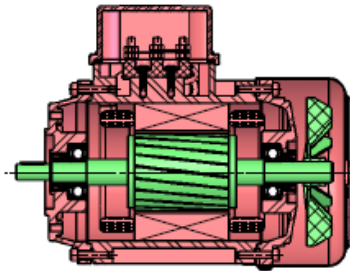


Systeme moteur



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A-A

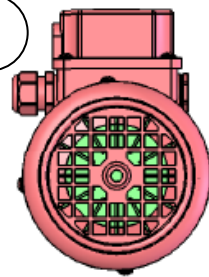


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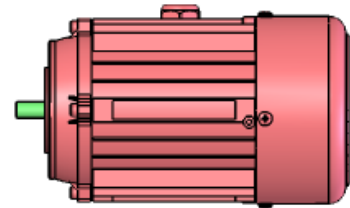
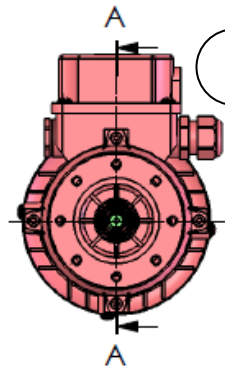
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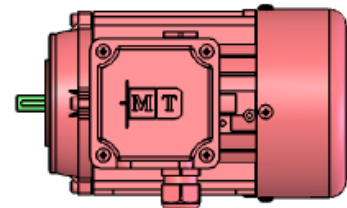
A



B

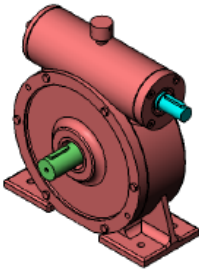


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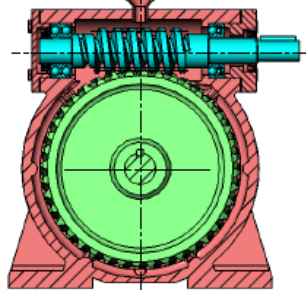
D

Systeme reducteur roue vis sans fin



...

B
A-A

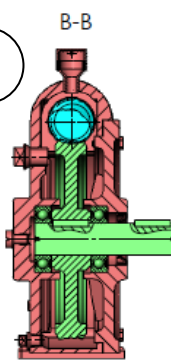


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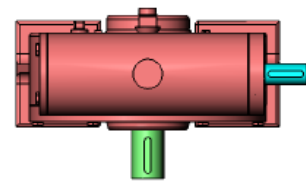
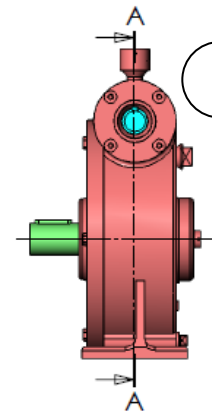
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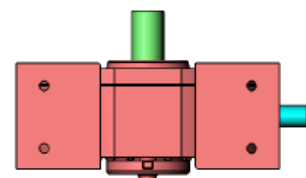
A



B



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D